

TITLE OF THE INVENTION

PROCESSING APPARATUS OF SHEETS

CROSS-REFERENCE TO RELATED APPLICATIONS

5 This application is based upon and claims the
benefit of priority from the prior Japanese Patent
Application No. 2000-396016, filed December 26, 2000,
the entire contents of which are incorporated herein by
reference.

BACKGROUND OF THE INVENTION

10 1. Field of the Invention

The present invention relates to a processing
apparatus of sheets, such as a classifying/sorting
apparatus of sheets using accumulation means of a vaned
wheel system, which classifies and sorts sheets such as
15 paper money or check, gift certificate, and other
securities by a type.

2. Description of the Related Art

For example, paper money or check, gift
certificate, or other securities, and the like function
20 as a key medium of social economic activities, and
gather in a large quantity in a specific position in a
process of circulation, and a business for sorting
these by a face value or a type is developed. In order
to automate this type of business or save energy, there
25 has been provided an apparatus called a paper money
classifying/sorting apparatus in which separate sheets
of paper money are supplied, distinguished, and

classified/accumulated by respective types (amounts of money), or formed in bundles each of 100 sheets.

This type of apparatus has a problem that the medium is flexible and it is therefore difficult to discharge a tip end of continuously fed paper money from a feeding path and accumulate the money in a laminate state. That is, the tip end of paper money collides against a rear end of another paper money or the tip end buckles by contact between paper money.

On the other hand, in a known accumulation apparatus of a vaned wheel system, a blade is rotated for about one or two blades with respect to about one sheet of continuously incoming paper money, and each sheet of paper money is introduced into a space formed in a gap among the blades. This is broadly utilized as a system in which collision between paper money does not occur or buckling does not occur by the contact of paper money.

That is, as shown in FIGS. 1, 2, paper money P horizontally held/fed by a pair of belts (not shown) is sorted by a gate device (not shown), and guided to a vaned wheel 101. Usually, the paper money P is accumulated in a horizontal state as shown in FIG. 1. Even in this vaned wheel system, there is a small probability that a tip end of the paper money P collides against a tip end 102a of a blade 102 of the vaned wheel 101 as shown in FIG. 2. In this case, a

problem is that the paper money P has the tip end thereof bent as shown by J, jumps out of the vaned wheel 101, and indicates an unstable behavior such as jam.

5 Moreover, when the aforementioned phenomenon occurs, the paper money P buckles in the blade 102 of the vaned wheel 101. Furthermore, when two sets of vaned wheels are used as usual, the paper money disadvantageously enters blades having different phases
10 in the two vaned wheels.

 Once the phenomenon arises even with a small arising frequency, this causes a serious problem in business. The paper money P is contaminated/damaged, and remains in an irregular position, and there is
15 disagreement in a counted number of sheets of paper money.

 A state of FIG. 1 may constantly be set in order to prevent the tip end of the blade of the vaned wheel from colliding against the tip end of the paper money.
20 Even in the conventional accumulation apparatus of the vaned wheel system, there is an example in which a taking-out device of the paper money is mechanically synchronized with rotation of the vaned wheel by a timing belt or the like, and the tip end of the paper
25 money is devised not to collide against the tip end of the blade.

 However, this system has not only a problem that a

mechanism for mechanical synchronization is expensive and complicated, but also a problem that it is impossible to handle a dispersion of a pitch between the paper money during actual taking-out and subsequent feeding.

That is, when the paper money is taken out, a taking-out pitch fluctuates by a subtle dispersion of friction force among the paper money. When the paper money is fed by a feeding belt, a pitch or a skew fluctuates by a change of feeding speed caused by a change of a belt property by temperature, or irregular contact with respect to a guide plate.

Moreover, for example, in Jpn. Pat. Appln. KOKAI Publication No. 59-153756, there is disclosed a technique in which a number of rotations of the vaned wheel is set to be variable, a passing timing of the paper money is measured in the feeding path in the vicinity of the vaned wheel, a feeding deviation per sheet of paper money is fed back, and the timing is synchronized with that of the vaned wheel.

However, in this system, the phase of the blade has to be controlled for each sheet with an immediately previous signal, and a high-speed response property is demanded. There is a problem that the system becomes expensive and control stability is poor. That is, there is a demand for an inexpensive system in which synchronization can be established between the vaned

wheel and the incoming paper money by a simple control.

BRIEF SUMMARY OF THE INVENTION

5 An object of the present invention is to provide a processing apparatus of sheets in which a rotation phase of a vaned wheel can be controlled to have an optimum phase, so that a tip end of a sheet of paper does not easily collide against a tip end of a blade with use of accumulation means of a vaned wheel system.

10 According to the present invention, there is provided a processing apparatus of sheets, comprising:

supply section configured to supply the sheets;

feeding section configured to feed the sheets supplied by the supply section;

15 a vaned wheel which has a plurality of blades, and which rotates, thereby allows the feed sheets to enter between the blades, and guides the sheets in a predetermined direction;

an accumulation section for accumulate the sheets guided by the vaned wheel;

20 at least two detection section, disposed at a predetermined interval in a feeding direction in a middle portion of the feeding section, for detecting the sheets feed by the feeding section;

25 measurement section configured to measure a passing time of the sheets feed by the feeding section in each detection section based on a detection result of each detection section;

calculation section configured to obtain a control amount of a rotation phase of the vaned wheel from a measurement result of the measurement section; and

5 control section configured to control the rotation phase of the vaned wheel in accordance with the control amount obtained by the calculation section.

Moreover, according to the present invention, there is provided a processing apparatus of sheets, comprising:

10 supply section configured to supply the sheets sheet by sheet;

feeding section configured to feed the sheets supplied by the supply section;

15 detection section configured to detect a type of the sheets from the sheets feed by the feeding section;

sorting section configured to sort the sheets feed by the feeding section in accordance with a detection result of the detection section;

20 a vaned wheel which has a plurality of blades arranged at a predetermined interval in a rotation direction, and which rotates, thereby allows the sheets sorted by the sorting section to enter between the blades, and guides the sheets in a predetermined direction;

25 an accumulation section for accumulate the sheets guided by the vaned wheel;

at least two detection section, disposed at a

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predetermined interval in a middle portion of the feeding section, for detecting the sheets feed by the feeding section;

5 measurement section configured to measure a tip-end passing time of the sheets feed by the feeding section in each detection section based on a detection result of the detection section;

10 calculation section configured to obtain a control amount of a rotation phase of the vaned wheel from a measurement result of the measurement section; and

control section configured to control the rotation phase of the vaned wheel in accordance with the control amount obtained by the calculation section.

15 Additional objects and advantages of the invention will be set forth in the description which follows, and in part will be obvious from the description, or may be learned by practice of the invention. The objects and advantages of the invention may be realized and obtained by means of the instrumentalities and
20 combinations particularly pointed out hereinafter.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWING

The accompanying drawings, which are incorporated in and constitute a part of the specification, illustrate embodiments of the invention, and
25 together with the general description given above and the detailed description of the embodiments given below, serve to explain the principles of the

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invention.

FIGS. 1 and 2 are explanatory views of a conventional accumulation apparatus of a vaned wheel system.

5 FIG. 3 is a side view schematically showing an internal constitution of a paper money classifying/sorting apparatus according to an embodiment of the present invention.

10 FIG. 4 is an explanatory view of an attitude of paper money supplied from a paper money supply section.

FIG. 5 is a plan view showing a constitution of a vaned wheel and a periphery thereof.

FIG. 6 is a side view showing a constitution of the vaned wheel.

15 FIG. 7 is a perspective view showing a constitution of the vaned wheel and the periphery thereof.

FIG. 8 is a side view showing a constitution of the vaned wheel and the periphery thereof.

20 FIG. 9 is an explanatory view of a first feeding path of the paper money.

FIG. 10 is an explanatory view of a second feeding path of the paper money.

25 FIG. 11 is an explanatory view of a third feeding path of the paper money.

FIG. 12 is an explanatory view of a fourth feeding path of the paper money.

FIGS. 13A and 13B are a constitution diagram schematically showing a controller for mainly performing synchronous control of the vaned wheel and an associated portion.

5 FIGS. 14A to 14G are timing charts showing synchronous control of the vaned wheel.

FIG. 15 is a flowchart showing the synchronous control of the vaned wheel.

10 FIG. 16 is a flowchart showing a skew correction control of the vaned wheel.

DETAILED DESCRIPTION OF THE INVENTION

An embodiment of the present invention will be described hereinafter with reference to the drawings.

A first embodiment will first be described.

15 FIG. 3 schematically shows an internal constitution of a paper money classifying/sorting apparatus as a processing apparatus of sheets according to an embodiment of the present invention. In FIG. 3, a reference numeral 1 denotes a housing. A table
20 section 1A is disposed in a middle portion on one side of the housing 1, and a paper money supply section 2 as supply means is disposed in the table section 1A. A plurality of sheets of paper money P as sheets are contained in an erected state in the paper money supply
25 section 2. The paper money P is pressed onto delivery rollers 5 by a backup plate 4 which is urged by a spring 3.

The paper money P set in the paper money supply section 2 is taken out separately sheet by sheet by rotation of the delivery rollers 5, and held/fed by a clamp type feeding path 31 constituted of a belt 6 and rollers 7 as feeding means. An attitude correction device 8 for automatically correcting shift and skew of the taken-out paper money P is disposed in the feeding path 31. Since the attitude correction device 8 is not directly related with the scope of the present invention, the description thereof is omitted, but details are described, for example, in Jpn. Pat. Appln. No. 2000-82593.

A discrimination section 9 as detection means is disposed on a downstream side in a paper money feeding direction of the feeding path 31. The discrimination section 9 optically and magnetically reads each type of information from a surface of the paper money P fed by a pair of rollers 10 as feeding means, logically processes the information, compares the information with reference information, and distinguishes dirt, presence/absence of breakage, money amount (type), four directions of top/bottom and front/back, and the like. When a pattern on the paper money P is correctly erected or vertically disposed, the top/bottom is judged to be correct. When the pattern on the paper money P is vertically reversed by 180 degrees, the top/bottom is judged to be reversed.

A first branch device 11 as switching means is disposed on the downstream side of the paper money feeding direction of the discrimination section 9. The first branch device 11 guides paper money which is not judged to be regular, such as double taken paper money, and paper money having a skew larger than a defined skew into a reject box 12 by distinction by the discrimination section 9. Alternatively, the device guides paper money which is judged to be regular in a second branch device 13 as switching means.

The second branch device 13 divides the feeding direction of the paper money P into first and second directions. A left/right reverse path 14 is disposed in the first direction, and a twist belt 15 for reversing left/right of the paper money P by 180 degrees is disposed in the left/right reverse path 14. A simple belt feeding section 16 is disposed in the second direction, and the paper money P is held or fed as it is. The paper money P branched and fed in the first and second directions joins one another in a junction section 17. Two path lengths extending to the junction section 17 are set to be equal to each other, and an interval of joined paper money does not deviate.

A third branch device 18 as switching means is disposed on the downstream side of the paper money feeding direction of the junction section 17. The third branch device 18 branches the feeding direction

of the paper money P into third and fourth directions.
A switch-back path section 19 is disposed in the third
direction. A reverse box 20 into which the paper money
P is introduced, and a beating wheel 21 for pressing a
5 rear end of the paper money P guided into the reverse
box 20 against a reverse roller 21a are disposed in the
switch-back path section 19. When the paper money P is
fed out of the reverse box 20, the paper money has the
top/bottom thereof reversed and is fed.

10 A simple belt feeding section 22 is disposed in
the fourth direction, and the paper money P is fed
while maintaining an attitude thereof as it is. The
paper money P branched and fed in the third and fourth
directions joins one another in a junction section 23.
15 Lengths of branch paths extending to the junction
section 23 are set to be equal, and the interval after
joining does not deviate.

A horizontal feeding path 24 as feeding means is
disposed on the downstream side of the paper money
20 feeding direction of the junction section 23. Branch
devices 25a to 25d as sorting means whose number is
less than a number of portions to be sorted by one are
disposed in the horizontal feeding path 24. First to
fourth classified pocket sections 26a to 26d are
25 disposed as accumulation sections under the branch
devices 25b to 25d. The paper money P is stacked and
accumulated in a horizontal state in these classified

pocket sections 26a to 26d.

A 100-sheets bundling device 27 is disposed under the branch device 25a. The 100-sheets bundling device 27 is constituted of: an accumulation section 28 for
5 accumulating and sorting every 100 sheets of paper money P; a feeding section 28a for feeding the paper money P from the accumulation section 28; and a banding section 29 for binding the paper money P fed by the feeding section 28a with a paper band 30.

10 An optical sensor S1 as detection means for detecting the paper money P passed toward the attitude correction device 8 through the feeding path 31 is disposed in a feeding end of the feeding path 31 immediately after the delivery rollers 5. Moreover, an
15 optical sensor S2 as detection means for detecting the paper money P passed toward the second branch device 13 through the sensor is disposed between the first branch device 11 and the second branch device 13. Furthermore, an optical sensor S3 as detection means for
20 detecting the paper money P passed toward the accumulation section through the feeding path 24 is disposed before the branch device 25a (accumulation section).

FIG. 4 shows the attitude of the paper money P
25 supplied from the paper money supply section 2. That is, the paper money P, a note, and the like differ in size with a face value. Therefore, when these are

collectively set in the paper money supply section 2,
and even when they are manually aligned, small-sized
paper money is buried in a maximum size, and there is a
high possibility of a left/right position deviation and
skewing.

That is, middle-sized paper money FR having a
front facing upwards and a reversed top/bottom
(hereinafter referred to as an FR note) has little
left/right position deviation, but is skewed to the
right. Paper money BF following the FR note and having
a back facing upwards and a normal top/bottom direction
(hereinafter referred to as a BF note) deviates on a
left side, and is skewed to the left. Moreover, paper
money BR following the BF note and having the back
facing upwards and a reversed top/bottom direction
(hereinafter referred to as a BR note) is not skewed
and does not deviate. Additionally, paper money
supplied following the BR note and having the front
facing upwards and the normal top/bottom direction is
regular and called an FF note.

Respective vaned wheels as main constituting
elements of the present invention are disposed in upper
portions of the classified pocket sections 26a to 26d
and accumulation section 28, and are constituted, for
example, as shown in FIGS. 5 to 8.

For example, constitutions of vaned wheels 114a,
114b, and the like disposed in the upper portion of the

accumulation section 28 will be described.

That is, three feeding belts 110a, 110b, 110c as feeding means are disposed in parallel to a feeding surface in the upper portion of the accumulation section 28. Each belt is constituted of a pair of belts 111, 112, and rotated by a roller 113, and the paper money P is held/fed by a holding force of the pair of belts 111, 112.

The vaned wheels 114a, 114b for accepting and guiding the fed paper money P in a predetermined direction are coaxially disposed between the respective feeding belts 110a, 110b, 110c. Each of the vaned wheels 114a, 114b is constituted by attaching a plurality of blades 116, ... in equally divided positions of a circumference of a cylindrical member 115, and the paper money P is guided into a space formed by two adjoining blades 116, 116. The paper money P guided by the vaned wheels 114a, 114b is guided into the accumulation section 28 positioned in the vicinity of a position under the vaned wheel, and laminated/accumulated.

The vaned wheels 114a, 114b are fixed to tip ends of rotation shafts 120a, 120b, respectively, and other ends of the rotation shafts 120a, 120b are connected to stepping motors 117a, 117b. Thereby, two sets of vaned wheels 114a, 114b are driven by the respective independent stepping motors 117a, 117b so that a

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rotation step number per unit time can change.

Moreover, rotation discs 118a, 118b each having a hole in one position in an outer peripheral portion of the disc are fixed to respective rotation shafts of the stepping motors 117a, 117b, and optical sensors 119a, 119b for detecting hole positions of the rotation discs 118a, 118b are disposed. When the optical sensors 119a, 119b detect the positions of the holes of the rotation discs 118a, 118b, each of the vaned wheels 114a, 114b outputs a signal of one pulse for each rotation. The signals are used as reference signals SG1a, SG1b of rotation of the vaned wheels 114a, 114b.

Moreover, with respect to the vaned wheels 114a, 114b, stepping motors 117a, 117b, and optical sensors 119a, 119b of the accumulation section 28, vaned wheels 114c, 114d, pocket stepping motors 117c, 117d, and optical sensors 119c, 119d correspond in the pocket section 26a corresponding to a given denomination or a state of sheets. Vaned wheels 114e, 114f, pocket stepping motors 117e, 117f, and optical sensors 119e, 119f correspond in the pocket section 26b corresponding to a given denomination or a state of sheets. Vaned wheels 114g, 114h, pocket stepping motors 117g, 117h, and optical sensors 119g, 119h correspond in the pocket section 26c corresponding to a given denomination or a state of sheets. Vaned wheels 114i, 114j, stepping motors 117i, 117j, and optical sensors 119i, 119j

correspond in the pocket section 26d corresponding to a given denomination or a state of sheets.

Moreover, signals from the optical sensors 119c, 119d are used as reference signals SG1c, SG1d of rotation of the vaned wheels 114c, 114d. Signals from the optical sensors 119e, 119f are used as reference signals SG1e, SG1f of rotation of the vaned wheels 114e, 114f. Signals from the optical sensors 119g, 119h are used as reference signals SG1g, SG1h of rotation of the vaned wheels 114g, 114h.

With respect to portions other than the aforementioned portions, the same reference numeral is attached and description is omitted.

The paper money P guided by the vaned wheels 114c, 114d is guided to the classified pocket section 26a positioned in the vicinity of a position under the vaned wheel, and laminated/accumulated. The paper money P guided by the vaned wheels 114e, 114f is guided to the classified pocket section 26b positioned in the vicinity of the position under the vaned wheel, and laminated/accumulated. The paper money P guided by the vaned wheels 114g, 114h is guided to the classified pocket section 26c positioned in the vicinity of the position under the vaned wheel, and laminated/accumulated. The paper money P guided by the vaned wheels 114i, 114j is guided to the classified pocket section 26d positioned in the vicinity of the position

under the vaned wheel, and laminated/accumulated.

FIGS. 9 to 12 show feeding paths a to d of the paper money P. When the branch devices 11, 13, 18 are driven/controlled in accordance with a distinction
5 result of the discrimination section 9, the feeding paths a to d are selectively set.

That is, when the discrimination section 9 distinguishes the paper money P as the FF note, the feeding path a shown in FIG. 9 is set. When the paper
10 money P is distinguished as the FR note, the feeding path b shown in FIG. 10 is set. When the paper money P is distinguished as the BF note from the direction thereof, the feeding path c shown in FIG. 11 is set. When the paper money P is distinguished as the BR note,
15 the feeding path d shown in FIG. 12 is set.

The paper money P passes through the switch-back path 19 in the feeding path a of FIG. 9. The paper money P passes through the left/right reverse path 14 in the feeding path b of FIG. 10. The paper money P
20 passes through the left/right reverse path 14 and switch-back path 19 in the feeding path c of FIG. 11. The paper money P does not pass through the left/right reverse path 14 switch-back path 19 in the feeding path d of FIG. 12.

25 Since the paper money P is fed in any one of the feeding paths a to d, the paper money having the front/back and top/bottom all aligned enters the

horizontal feeding path 24. Therefore, the paper money
P classified by the type is laminated in the horizontal
state in the classified pockets 26a to 26d while the
front/back and top/bottom are all aligned. The paper
5 money P can be wound with the paper band 30 even in the
100-sheets bundling device 27 while the front/back and
top/bottom are aligned.

FIGS. 13A and 13B schematically shows a controller
for performing synchronous control of the vaned wheels
114a to 114j. In FIG. 13, respective output signals of
the sensors S1, S2, S3 are sent to a central processing
unit (CPU) 120 as control means. The CPU 120 performs
a whole operation control and various types of
processing, and is connected to an oscillator 121. The
15 oscillator 121 generates a reference signal (pulse) SG0
having a constant period as a reference of the control.

The CPU 120 is connected to driving circuits 122a
to 122e. The stepping motors 117a, 117b are driven/
controlled by the driving circuit 122a. The stepping
20 motors 117c, 117d are driven and controlled by the
driving circuit 122b. The stepping motors 117e, 117f
are driven/controlled by the driving circuit 122c. The
stepping motors 117g, 117h are driven and controlled by
the driving circuit 122d. The stepping motors 117i,
25 117j are driven/controlled by the driving circuit 122e.
Respective output signals SG1a to SG1j of the optical
sensors 119a to 119j are sent to the CPU 120.

The synchronous control of the vaned wheels 114a, 114b, 114c, 114d in the aforementioned constitution will next be described with reference to timing charts shown in FIGS. 14A to 14G, a flowchart shown in FIG. 15, and FIGS. 13A and 13B.

First, an initial setting of synchronization will be described.

In the present embodiment, it is assumed that a number of sheets n of the paper money P taken out by the delivery rollers 5 in the paper money supply section 2 is 20 sheets ($n = 20$) per second. Moreover, the reference of the control is the reference signal (pulse) $SG0$ which is outputted by the oscillator 121 and which has a period of $1/n = 50$ ms as shown in FIG. 14A. That is, the reference signal $SG0$ corresponds to a supply timing of the paper money P supplied sheet by sheet from the paper money supply section 2.

When power is turned on (ST1), each feeding belt is rotated and driven at a reference speed of $S0 = 2.0$ m/second by an alternating-current motor (ST2).

Additionally, in the paper money supply section 2, the delivery roller 5 is controlled so that there is an equal distance from the tip end of the paper money P to the tip end of the next paper money P , and a pitch between the paper money is $S0/n = 100$ mm.

When the apparatus starts supplying the paper

money P, the CPU 120 generates a paper money delivery
signal at a rising timing of the reference signal SG0
from the oscillator 121, and sends the signal to a
driving circuit (not shown) of the delivery roller 5,
5 and the paper money P is delivered. For a timing at
which the delivered paper money P passes through the
sensor S1, a deviation amount $\Delta ts1$ from the reference
signal SG0 indicates a constant value, and can be known
beforehand, as long as the paper money P is correctly
10 delivered.

Moreover, with a constant reference feeding speed,
it is also possible to calculate a deviation amount
 $\Delta ts3$ from the reference signal SG0 when the tip end of
the paper money P passed through the sensor S1 with the
15 deviation amount $\Delta ts1$ reaches entrances of the vaned
wheels 114a, 114b.

It is assumed that the sensor S1 for detecting the
paper money P fed in the feeding path is disposed
immediately after taking-out of the paper money P, the
20 sensor S2 is disposed after the branch device 11 for
distributing a regular note and a rejected note, and
the sensor S3 is disposed immediately before the vaned
wheels 114a, 114b. For respective distances, it is
assumed that, for example,

25 a distance between S1 and S2 is $L1 \text{ (mm)} = 2400 \text{ mm}$,
a distance between S2 and S3 is $L2 \text{ (mm)} = 1300 \text{ mm}$,
and

a distance between S3 and the tip end of the vaned wheel is $L3 \text{ (mm)} = 300 \text{ mm}$.

Then, a distance between the sensor S1 and the vaned wheels 114a, 114b is $(L1+L2+L3) \text{ (mm)} = 4000 \text{ mm}$. In this case, when unit systems (mm) and (msec) are used, the following results.

$$\begin{aligned} X &= ((L1+L2+L3)/S0+\Delta t_{s1})/(1/n) \dots (1) \\ &= ((4000/2)\text{ms}+\Delta t_{s1})/50 \text{ ms} \end{aligned}$$

Then, an integer remainder of a calculation result X of the above equation (1) is the deviation amount Δt_{s3} . The deviation amount Δt_{s3} is a positive number, and is a delay time from the reference signal SG0 when the tip end of the paper money P reaches the vaned wheels 114a, 114b.

On the other hand, it is assumed that the output signals of the optical sensors 119a, 119b each outputting the signal once per rotation are SG1a, SG1b as shown in FIGS. 14B, 14C. Additionally, these signals SG1a, SG1b are outputted where the blade comes to the position of FIG. 1. That is, the tip end of the paper money P is substantially in a middle between the blades. For example, with 16 blades, the tip end is in a tenth position obtained by dividing a blade pitch of 22.5 degrees into nine pitches each of 2.5 degrees.

For a reference rotation number Fr of each of the vaned wheels 114a, 114b,, a rotation number of 16 reference signals SG0 per rotation is initially set as

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a rotation speed, assuming that one piece of paper
money P enters with rotation of one blade (1/16
rotation) among 16 blades in one circumference. When
the vaned wheels 114a, 114b are rotated in this manner
5 (ST3), the respective stepping motors 117a, 117b are
asynchronous, and therefore the signal SG1a or SG1b
outputted for each rotation generates a timing
deviation amount Δta or Δtb with respect to the
reference signal SG0 as shown in FIGS. 14B, 14C. The
10 amount is measured in the CPU 120 (ST4).

When the tip end of the fed paper money P reaches
the tip end of the vaned wheel 114a or 114b, the blade
of the vaned wheel 114a or 114b comes at a tenth time
of FIG. 1. For this, the following results:

15
$$Y_a = (\Delta ta - \Delta ts_3) / (1/n) \dots (2); \text{ and}$$

$$Y_b = (\Delta tb - \Delta ts_3) / (1/n) \dots (3).$$

Integer remainders Δta_a , Δtb_a of calculation results
 Y_a , Y_b of the above equations (2) and (3) are obtained
(ST5). When the value Δta_a or Δtb_a indicates a
20 positive number, the vaned wheels 114a, 114b are
delayed with respect to a reaching time of the paper
money P. With a negative number, the vaned wheels
114a, 114b advance with respect to the reaching time of
the paper money P. When the vaned wheels 114a, 114b
25 advance, the vaned wheels are decelerated for a
predetermined time. When the vaned wheels are delayed,
the vaned wheels are accelerated for a predetermined

time (ST6). Thereby, the reference feeding speed is assumed, and the vaned wheels 114a, 114b can be synchronized with an entering timing of the paper money P.

5 Moreover, it is also possible to calculate a deviation amount $\Delta ts3'$ from the reference signal SG0 when the tip end of the paper money P passed through the sensor S1 with the deviation amount $\Delta ts1$ reaches the entrances of the vaned wheels 114c, 114d.

10 It is assumed that the sensor S1 for detecting the paper money P fed in the feeding path is disposed immediately after the taking-out of the paper money P, the sensor S2 is disposed behind the branch device 11 for distributing the regular note and rejected note, 15 and the sensor S3 is disposed before the vaned wheels 114c, 114d. For the respective distances, it is assumed that, for example,

 the distance between S1 and S2 is $L1$ (mm),

 the distance between S2 and S3 is $L2$ (mm), and

20 the distance between S3 and the tip end of the vaned wheel is $(L4)$ (mm). Then, the distance between the sensor S1 and the vaned wheels 114c, 114d is $(L1+L2+L4)$ (mm). In this case, when unit systems (mm) and (msec) are used, the following results.

25
$$X = ((L1+L2+L4)/S0+\Delta ts1)/(1/n) \dots (1)$$
$$= ((4000/2)ms+\Delta ts1)/50 \text{ ms}$$

Then, the integer remainder of the calculation result X

of the above equation (1) is the deviation amount $\Delta t_{s3'}$. The deviation amount $\Delta t_{s3'}$ is a positive number, and is a delay time from the reference signal SG0 when the tip end of the paper money P reaches the
5 vaned wheels 114c, 114d.

On the other hand, it is assumed that the output signals of the optical sensors 119c, 119d each outputting the signal once per rotation of the vaned wheels 114c, 114d are SG1c, SG1d as shown in FIGS. 14D,
10 14E. Additionally, these signals SG1c, SG1d are outputted where the blade comes to the position of FIG. 2. That is, the tip end of the paper money P is substantially in the middle between the blades. For example, with 16 blades, the tip end is in the tenth
15 position obtained by dividing the blade pitch of 22.5 degrees into nine pitches each of 2.5 degrees.

For the reference rotation number F_r of each of the vaned wheels 114a, 114b, the rotation number of 16 reference signals SG0 per rotation is initially set as
20 a reference speed, assuming that one piece of paper money P enters with rotation of one blade (1/16 rotation) among 16 blades in one circumference. When the vaned wheels 114c, 114d are rotated in this manner (ST3), the respective stepping motors 117c, 117d are
25 asynchronous, and therefore the signal SG1c or SG1d outputted for each rotation generates a timing deviation amount Δt_c or Δt_d with respect to the

reference signal SG0 as shown in FIGS. 14D, 14C. The amount is measured in the CPU 120 (ST4).

When the tip end of the fed paper money P reaches the tip end of the vaned wheel 114c or 114d, the blade of the vaned wheel 114c or 114d comes a tenth time of FIG. 2. For this, the following results:

$$Yc = (\Delta tc - \Delta ts3') / (1/n) \dots (2); \text{ and}$$

$$Yd = (\Delta td - \Delta ts3) / (1/n) \dots (3).$$

Integer remainders Δtca , Δtda of calculation results Yc , Yd of the above equations (2) and (3) are obtained (ST5). When the value Δtca or Δtda indicates a positive number, the vaned wheels 114a, 114b are delayed with respect to the reaching time of the paper money P. With the negative number, the vaned wheels 114c, 114d advance with respect to the reaching time of the paper money P. When the vaned wheels 114c, 114d advance, the vaned wheels are decelerated for a predetermined time. When the vaned wheels are delayed, the vaned wheels are accelerated for a predetermined time (ST6). Thereby, the reference feeding speed is assumed, and the vaned wheels 114c, 114d can be synchronized with the entering timing of the paper money P.

Moreover, similarly as described above, it is possible to establish synchronization between the other vaned wheels 114e, ... and the entering timing of the paper money P.

This operation is performed as an initial setting in a type in which the feeding path is usually rotated with the power turn on before issuance of a supply start command of the paper money P.

5 Synchronization setting corresponding to a fluctuation of the feeding speed will next be described.

First, when the CPU 120 starts supplying the paper money P (ST7), the sensors S1 and S2 disposed in the feeding path detect the passing of the paper money P, and each detection signal is sent to the CPU 120. As shown in FIGS. 14F, 14G, the CPU 120 calculates a passing time Δt_{L1} for which each paper money P is fed to the sensor S2 from S1 is calculated based on the respective detection signals of the sensors S1, S2. This time is obtained for a plurality of continuous sheets (e.g., 20 sheets), an average value is calculated, a feeding distance L1 is divided by the average value, and an average speed S_{vv} ($=L1/\Delta t_{L1}$) is obtained (ST8).

20 A time ΔT in which the paper money P arrives at the tip end of the vaned wheels 114a, 114b from the sensor S1 is obtained from the average speed S_{vv} as follows.

$$\Delta T = (L1+L2+L3)/S_{vv} \dots (4)$$

25 On the other hand, a time ΔT_0 in which the paper money is to arrive is obtained from a reference feeding speed S_0 as follows.

$$\Delta T_0 = (L_1 + L_2 + L_3) / S_0 \dots (5)$$

$$\Delta T_0 - \Delta T = ((L_1 + L_2 + L_3) / S_0) - ((L_1 + L_2 + L_3) / S_{vv}) = \Delta f \dots (6)$$

Here, Δf is an error (time difference) generated by a difference from the reference speed as a result of fluctuation of an actual speed of the feeding path with a friction load, temperature change, and change with elapse of time. When the error indicates a plus value, occurrence of a delay is indicated. A minus value indicates occurrence of an advance (ST9).

Additionally, here, it is assumed that ΔA is a [remainder] of integer division of $\Delta f / (1/n)$. In the aforementioned initial setting, since the vaned wheels 114a, 114b are synchronized with the reference signal SG0, a control amount ΔC of deviation with fluctuation of feeding speed of the paper money P is as follows (ST10).

$$Z = \Delta A / (1/n) \dots (7)$$

When a quotient of the equation (7) has a value of "0" or a positive value, a tip-end position of the paper money P is delayed with respect to the tip-end position of the vaned wheels 114a, 114b. A negative value indicates an advance. A driving pulse rate of the stepping motors 117a, 117b is changed so that the integer remainder (ΔC) of a calculation result Z is "0" (ST11). By the control, in the average value of the feeding pitch dispersion of the paper money P, the tip end of the paper money P contained in the accumulation

section 28 can enter a middle position of the vaned wheels 114a, 114b.

Moreover, a time $\Delta T'$ in which the paper money P arrives at the tip end of the vaned wheels 114c, 114d from the sensor S1 is obtained from the average speed S_{vv} as follows.

$$\Delta T' = (L1+L2+L4)/S_{vv} \dots (4)$$

On the other hand, a time $\Delta T0'$ in which the paper money is to arrive is obtained from the reference feeding speed $S0$ as follows.

$$\Delta T0' = (L1+L2+L4)/S0 \dots (5)$$

$$\Delta T0' - \Delta T' = ((L1+L2+L4)/S0) - ((L1+L2+L4)/S_{vv}) = \Delta f' \dots (6)$$

Here, $\Delta f'$ is an error (time difference) generated by the difference from the reference speed as the result of fluctuation of the actual speed of the feeding path with the friction load, temperature change, and change with elapse of time. When the error indicates the plus value, occurrence of delay is indicated. The minus value indicates occurrence of advance (ST9).

Additionally, here, it is assumed that $\Delta A'$ is a [remainder] of integer division of $\Delta f'/(1/n)$. In the aforementioned initial setting, since the vaned wheels 114c, 114d are synchronized with the reference signal $SG0$, a control amount $\Delta C'$ of deviation with the fluctuation of feeding speed of the paper money P is as

follows (ST10).

$$Z = \Delta A' / (1/n) \dots (7)$$

When the quotient of the equation (7) has the value of "0" or the positive value, the tip-end position of the paper money P is delayed with respect to the tip-end position of the vaned wheels 114c, 114d. The negative value indicates the advance. The driving pulse rate of the stepping motors 117c, 117d is changed so that the integer remainder ($\Delta C'$) of the calculation result Z is "0" (ST11). By the control, in the average value of the feeding pitch dispersion of the paper money P, the tip end of the paper money P contained in the classified pocket 26a can enter the middle position of the vaned wheels 114c, 114d.

Moreover, similarly as described above, in the average value of the feeding pitch dispersion of the paper money P, the tip end of the paper money P contained in each of the classified pockets 26b, 26c, 26d can enter the corresponding middle position of each of the vaned wheels 114e, 114f, 114g, 114h, 114i, 114j.

A second embodiment will next be described with reference to a flowchart shown in FIG. 15.

According to the aforementioned first embodiment, collision of the tip end of the paper money P against the blades of the vaned wheels 114a, 114b (114c to 114j) can considerably be prevented.

However, when the paper money P is skewed and fed

as shown in FIG. 5, the left and right vaned wheels 114a, 114b (114c and 114d, 114e and 114f, 114g and 114h, or 114i and 114j) rotate in the same phase. Therefore, a possibility of collision of the tip end of the paper money P against the vaned wheel on any side arises. On the other hand, it is assumed that the sensor S3 is divided into two sensors S3a, S3b, and these sensors are arranged in a direction crossing at right angles to the feeding direction of the paper money P. Then, a skew amount ΔK of the paper money P can be measured.

That is, in the second embodiment, similarly as the first embodiment, an average estimated reaching time is calculated from a feeding state of several tens of sheets after start of taking-out (ST21). That is, the CPU 120 calculates a time in which the paper money P reaches the tip end of the vaned wheels 114a, 114b from the sensor S1, a time in which the paper money P reaches the tip end of the vaned wheels 114c, 114d from the sensor S1, a time in which the paper money P reaches the tip end of the vaned wheels 114e, 114f from the sensor S1, a time in which the paper money P reaches the tip end of the vaned wheels 114g, 114h from the sensor S1, and a time in which the paper money P reaches the tip end of the vaned wheels 114i, 114j from the sensor S1.

Following this calculation, the CPU 120 controls

the vaned wheels 114a to 114j in a predetermined phase (ST22). (corresponding to the steps 1 to 11 of the first embodiment)

5 In a controlled state, the CPU 120 measures the skew amount ΔK (ST23), and calculates a deviation amount Δk_s from an initial estimated reaching time (ST24), every time the paper money P stored in the accumulation section 28 passes through the sensors S3a, S3b. Only when the deviation amount Δk_s is larger than
10 a predetermined amount (ST25), phases of the vaned wheels 114a, 114b are separately controlled (ST26).

Moreover, the CPU 120 measures the skew amount ΔK (ST23), and calculates the deviation amount Δk_s from the initial estimated reaching time (ST24), every time
15 the paper money P stored in the classified pocket section 26a passes through the sensors S3a, S3b. Only when the deviation amount Δk_s is larger than the predetermined amount (ST25), the phases of the vaned wheels 114c, 114d are separately controlled (ST26).

20 Furthermore, the CPU 120 measures the skew amount ΔK (ST23), and calculates the deviation amount Δk_s from the initial estimated reaching time (ST24), every time the paper money P stored in the classified pocket section 26b passes through the sensors S3a, S3b. Only
25 when the deviation amount Δk_s is larger than the predetermined amount (ST25), the phases of the vaned wheels 114e, 114f are separately controlled (ST26).

FIG. 4

Additionally, the CPU 120 measures the skew amount ΔK (ST23), and calculates the deviation amount Δk_s from the initial estimated reaching time (ST24), every time the paper money P stored in the classified pocket section 26c passes through the sensors S3a, S3b. Only when the deviation amount Δk_s is larger than the predetermined amount (ST25), the phases of the vaned wheels 114g, 114h are separately controlled (ST26).

Moreover, the CPU 120 measures the skew amount ΔK (ST23), and calculates the deviation amount Δk_s from the initial estimated reaching time (ST24), every time the paper money P stored in the classified pocket section 26d passes through the sensors S3a, S3b. Only when the deviation amount Δk_s is larger than the predetermined amount (ST25), the phases of the vaned wheels 114i, 114j are separately controlled (ST26).

This can prevent even the paper money P having a feeding dispersion deviating from the average or the paper money P having a skew from colliding against the vaned wheels 114a and 114b, 114c and 114d, 114e and 114f, 114g and 114h, or 114i and 114j.

Additionally, in the aforementioned example, the sensors S3a, S3b measure a skew amount, but the sensor for measure the skew amount may be disposed in the vicinity of the respective vaned wheels 114e and 114f, 114g and 114h, or 114i and 114j.

Moreover, the CPU has a multi-task structure, and

performs a delivery feeding control of the paper money,
simultaneously determines the control amount of the
vaned wheel from calculation of the feeding dispersion
and average reaching time, and gives an interrupt
5 signal to the feeding control.

A third embodiment will next be described.

Also according to the first and second
embodiments, the vaned wheels 114a, 114b are in a non-
controlled state with respect to first several tens of
10 sheets after start of processing. In this case, there
is a fear that the paper money P collides against the
tip end of the vaned wheels 114a, 114b. On the other
hand, correction amounts (control amounts) of the vaned
wheels 114a, 114b, ... immediately before supply start
15 of the paper money P (e.g., at an end of the previous
operation) are stored in an internal memory 120a of the
CPU 120 at the supply start. The correction amount can
be used to synchronize the phase of the vaned wheels
114a, 114b, ... before the supply start of the paper
20 money P. Additionally, the control of the first
embodiment may be performed.

As described above, according to the present
embodiment, without mechanically synchronizing the
taking-out device of the paper money and the rotation
25 of the vaned wheel, for example, by a timing belt as
conventional, the rotation phase of the vaned wheel can
be controlled so that the tip end of the paper money

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does not easily collide against the tip end of the blade. Moreover, there is no problem that the mechanism becomes expensive and complicated by the mechanical synchronization. The dispersion of the pitch between the paper money by the actual taking-out and subsequent feeding can be handled.

That is, during the taking-out, the taking-out pitch fluctuates by a subtle friction force dispersion between the paper money. In the feeding by the belt, the pitch or the skew fluctuates by the change of the feeding speed by the change of the belt property by the temperature, or the irregular contact with the guide plate. However, the actual delivery feeding state is measured and fed back and the rotation phase of the vaned wheel is controlled.

Particularly, with respect to the skew of the paper money, two vaned wheels are driven by separate motors, and can therefore be set in separate phase angles. This can also solve a problem that the skewed paper money enters positions of separate phases.

Additionally, in the aforementioned embodiment, a case in which the present invention is applied to the classifying/sorting apparatus of sheets for classifying and sorting the paper money by the type has been described, but the present invention is not limited to this. The present invention can similarly be applied, for example, to the processing apparatus of the sheets,

such as the classifying/sorting apparatus of the sheets which uses accumulation means of a vaned wheel system for classifying and sorting the sheets such as a check and gift certificate, and other securities by the type.

5 Additional advantages and modifications will readily occur to those skilled in the art. Therefore, the invention in its broader aspects is not limited to the specific details and representative embodiments shown and described herein. Accordingly, various
10 modifications may be made without departing from the spirit or scope of the general invention concept as defined by the appended claims and their equivalents.

FOOTNOTES